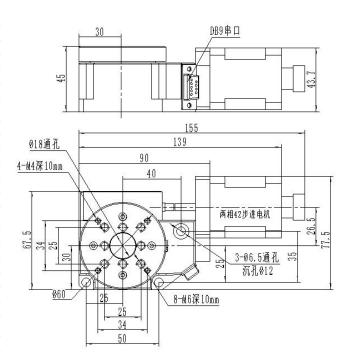
Electric module

DXZ-Rotating module

Product characteristics:

- *42 stepper motors are equipped as standard, and the motion controller can realize automatic control
- *The special structural design ensures the extremely low end jump and eccentricity of the rotating table, making the rotating motion more stable
- *The central through hole of the rotary table has strict coaxiality requirements with the rotary center, which is convenient for customers to make precise positioning
- *The worm gear and worm structure with precise research and matching is adopted, which has comfortable movement, can rotate in any forward and reverse direction, and has very little empty return
- *The scale ring on the periphery of the table is a laser marking scale, which is convenient for initial positioning and reading
- *The motor and worm are connected by using high-quality elastic coupling, with synchronous transmission and good depolarization performance, greatly reducing eccentric disturbance and low noise
- *The rotary table can be used horizontally or vertically, and can be combined with other kinds of products to form a multi-dimensional electric adjustment table

	Product model	KYCT160DXZ60H
	Platform size	Ф 60mm
	Rotation angle	360°
	Taterial Science	aluminium alloy
	surface treatment	Oxidation blackening
	load bearing	25kg (Transfer bearing
)		diameter Φ Within 120)
a	veight	1. 3kg
ı	transmission ratio	90 : 1
2	Driving mechanism	Worm gear and worm mechanism
ì.	Guide rail form	Bearing
ı	electric machinery	Stepper motor (1.8°)
l		0.02° (No subdivision)
	resolving power	0.001° =3.6"
		(20subdivision)
	Empty return	0.005° =18"
	eccentric	5μ
	Lose step	0.005° =18"
•	Parallelism	80ћ
	Taxinum speed	50°/sec
	positioning accuracy	0. 005° =18"
	Absolute positioning accuracy	0.01° =36″
	Origin error	±0.03°



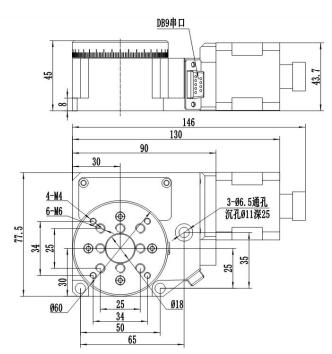


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Model and parameters

		1/4
	Product mode1	KYCT160DXZ60XH
	Platform size	Ф 60mm
	Rotation angle	360°
	T aterial Science	aluminium alloy
-	surface treatment	Oxidation blackening
	load bearing	25kg (Transfer bearing diameter Φ Within 120)
	veight	1. 3kg
	transmission ratio	90:1
	Driving mechanism	Worm gear and worm mechanism
- 5	Guide rail form	Bearing
×	electric machinery	Stepper motor (1.8°)
200	resolving power	0.02° (No subdivision) 0.001°=3.6" (20subdivision)
	Empty return	0.005° =18"
	eccentric	5μ
ě	Lose step	0.005° =18"
2	Parallelism .	80ћ
	Taxinun speed	50°/sec
80	positioning accuracy	0.005° =18"
000	Absolute positioning accuracy	0.01° =36″
	Origin error	± 0. 03°



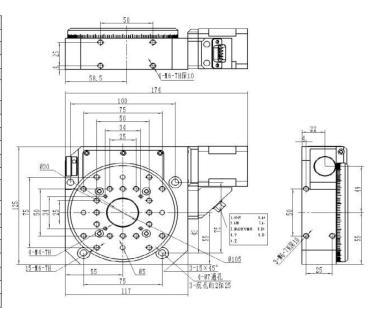


咨询电话: 15611318783

Product characteristics:

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- *The rotary table can be used horizontally or vertically, and can be combined with other kinds of products to form a multi-dimensional electric adjustment table

	Product model	KYCT110DXZ100H
	Platform size	Ф 105mm
	Rotation angle	360°
	Material Science	aluminium alloy
	surface treatment	Oxidation blackening
	load bearing	35kg (Transfer bearing diameter Φ Within 210)
	veight	3kg
	transmission ratio	90:1
糸	Driving mechanism	Worm gear and worm mechanism
9	Guide rail form	Bearing
参 数	electric machinery	Stepper motor (1.8°)
说明	resolving pover	0.02° (No subdivision) 0.001°=3.6" (20subdivision)
.91	Empty return	0.005° =18"
	eccentric	5µ
	Lose step	0.005° =18"
	Parallelis n	80ћ
	Taxinun speed	50°/sec
	positioning accuracy	0.005° =18"
	Absolute positioning	0.01° =36″
1	Origin error	±0.03°

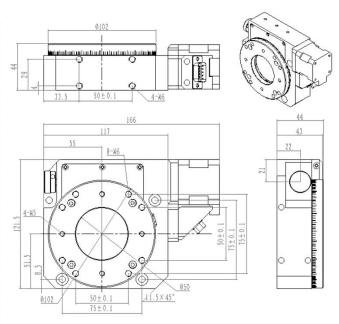




Product characteristics:

- *42 stepper motors are equipped as standard, and the motion controller can realize automatic control
- *The special structural design ensures the extremely low end jump and eccentricity of the rotating table, making the rotating motion more stable
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- *The scale ring on the periphery of the table is a laser marking scale, which is convenient for initial positioning and reading
- *The motor and worm are connected by using high-quality elastic coupling, with synchronous transmission and good depolarization performance, greatly reducing eccentric disturbance and low noise
- *The rotary table can be used horizontally or vertically, and can be combined with other kinds of products to form a multi-dimensional electric adjustment table

	Product mode1	KYCT110DXZ105H
	Platform size	Ф 105mm
	Rotation angle	360°
	Material Science	aluminium alloy
	surface treatment	Oxidation blackening
	load bearing	35kg (Transfer bearing diameter Φ Within 210)
	veight	3kg
	transmission ratio	90:1
	Driving mechanism	Worm gear and worm mechanism
	Guide rail form	Bearing
	electric machinery	Stepper motor (1.8°)
参数说明	resolving power	0.02° (No subdivision) 0.001°=3.6" (20subdivision)
	Empty return	0.005° =18"
	eccentric	5µ
	Lose step	0.005° =18"
	Parallelism	80ћ
	Taxinum speed	50°/sec
	positioning accuracy	0.005° =18"
	Absolute positioning	0.01° =36"
	Origin error	±0.03°

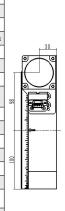


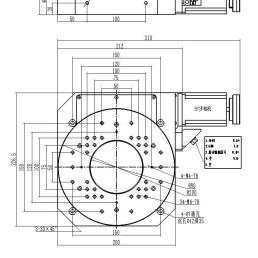


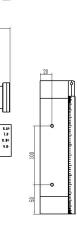
Product characteristics:

- *57 stepper motors are equipped as standard, and the motion controller can realize automatic control
- *The special structural design ensures the extremely low end jump and eccentricity of the rotating table, making the rotating motion more stable
- *The central through hole of the rotary table has strict coaxiality requirements with the rotary center, which is convenient for customers to make precise positioning
- *The worm gear and worm structure with precise research and matching is adopted, which has comfortable movement, can rotate in any forward and reverse direction, and has very little empty return
- *The scale ring on the periphery of the table is a laser marking scale, which is convenient for initial positioning and reading
- *The motor and worm are connected by using high-quality elastic coupling, with synchronous transmission and good depolarization performance, greatly reducing eccentric disturbance and low noise
- *The rotary table can be used horizontally or vertically, and can be combined with other kinds of products to form a multi-dimensional electric adjustment table

	Product model	KYCT110DXZ200H
	Platform size	Ф 200mm
	Rotation angle	360°
	Material Science	aluminium alloy
	surface treatment	Oxidation blackening
р	load bearing	55kg (Transfer bearing diameter Φ Within 400)
=	veight	8. 5kg
a	transmission ratio	180:1
r	Driving mechanism	Worm gear and worm mechanism
a	Guide rail form	Bearing
а	electric machinery	Stepper motor (1.8°)
m e	resolving power	0.02° (No subdivision) 0.001° =3.6" (20subdivision)
t	Empty return	0.005° =18"
	eccentric	5μ
e	Lose step	0.005° =18"
r	Parallelism	80н
	Taxinum speed	25° /sec
	positioning accuracy	0.005° =18"
	Absolute positioning accuracy	0. 01° =36″
	Origin error	±0.03°









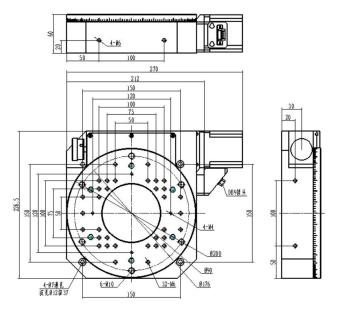
Electric module

DXZ-Rotating module

Product characteristics:

- *57 stepper motors are equipped as standard, and the motion controller can realize automatic control
- *The special structural design ensures the extremely low end jump and eccentricity of the rotating table, making the rotating motion more stable
- *The central through hole of the rotary table has strict coaxiality requirements with the rotary center, which is convenient for customers to make precise positioning
- *The worm gear and worm structure with precise research and matching is adopted, which has comfortable movement, can rotate in any forward and reverse direction, and has very little empty return
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- *The motor and worm are connected by using high-quality elastic coupling, with synchronous transmission and good depolarization performance, greatly reducing eccentric disturbance and low noise
- *The rotary table can be used horizontally or vertically, and can be combined with other kinds of products to form a multi-dimensional electric adjustment table

	Product mode1	KYCT110DXZ200GII
	Platform size	Ф 200mm
	Rotation angle	360°
	Material Science	aluminium alloy
	surface treatment	Oxidation blackening
р	load bearing	55kg (Transfer bearing diameter Φ Within 400)
0	weight	8. 5kg
a	transmission ratio	180: 1/90: 1
\mathbf{r}	Driving mechanism	Worm gear and worm mechanism
a	Guide rail form	Bearing
а	electric machinery	Stepper motor (1.8°)
m e	resolving power	0.02° (No subdivision) 0.001° =3.6″
t	Empty return	(20subdivision) 0.005°=18"
	eccentric	5μ
e	Lose step	0.005° =18"
\mathbf{r}	Parallelism	408
	Taxinum speed	25° /sec
	positioning accuracy	0.005° =18"
	Absolute positioning accuracy	0. 01° =36″
	Origin error	±0.03°

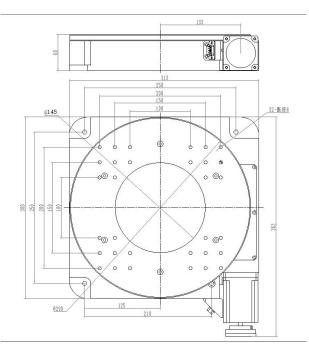




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- *57 stepper motors are equipped as standard, and the motion controller can realize automatic control
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- *The motor and worm are connected by using high-quality elastic coupling, with synchronous transmission and good depolarization performance, greatly reducing eccentric disturbance and low noise
- *The rotary table can be used horizontally or vertically, and can be combined with other kinds of products to form a multi-dimensional electric adjustment table

	Product mode1	KYCT110DXZ300H
	Platform size	Ф 300mm
	Rotation angle	360°
	Material Science	aluminium alloy
	surface treatment	Oxidation blackening
_	load bearing	85kg (Transfer bearing
\mathbf{p}		diameter Φ Within 600)
a	veight	10. 5kg
\mathbf{a}	transmission ratio	250:1
\mathbf{r}	Driving mechanism	Worm gear and worm mechanism
a	Guide rail form	Bearing
а	electric machinery	Stepper motor (1.8°)
m		0.02° (No subdivision)
e	resolving power	0. 001° =3. 6"
		(20subdivision)
t	Empty return	0.005° =18"
0	eccentric	5µ
e	Lose step	0.005° =18"
\mathbf{r}	Parallelis n	80н
	Taxinum speed	15°/sec
	positioning accuracy	0.005° =18"
	Absolute positioning accuracy	0. 01° =36″
	Origin error	± 0. 03°





Product characteristics:

- *Precision 42 stepping motor is equipped as standard, and the motion controller can realize automatic control of its two axes
- *The central through hole of the rotary table has strict coaxiality requirements with the rotary center, which is convenient for customers to make precise positioning
- *The worm gear and worm structure with precise research and matching is adopted, which has comfortable movement, can rotate in any forward and reverse direction, and has very little empty return
- *The table top is marked with standard fixed threads to facilitate customers to install relevant accessories by themselves
- *The two-dimensional rotary table can carry out two-axis linkage horizontally and form two-dimensional precise adjustment with its optical products

*The initial zero position is equipped as standard, and the error generated in long-term use can be zeroed and

eliminated Model and parameters KYCT110X160D2XZ360M Product model Platform size 90X165mm (\bigcirc) Rotation angle 360° Material Science aluminium alloy surface treatment Oxidation blackening load bearing 10kg p weight 6.5kg a transmission ratio 90:1 Driving mechanism Worm gear and worm mechanism r Guide rail form Bearing a electric machinery Stepper motor (1.8° m 0.02° (No subdivision) resolving power e 0.001° =3.6" (20subdivision) Empty return 0.005° =18" t eccentric 5μ 0. 005° =18" e Lose step Parallelism ж0я r Maximum speed 25° /sec*40° /sec positioning accuracy 0.005° =18" Absolute positioning 0.01° =36" accuracy Origin error ±0.05°



Product characteristics:

- *Precision 57 stepping motor is equipped as standard, and the motion controller can realize automatic control of its two axes
- *The central through hole of the rotary table has strict coaxiality requirements with the rotary center, which is convenient for customers to make precise positioning
- *The worm gear and worm structure with precise research and matching is adopted, which has comfortable movement, can rotate in any forward and reverse direction, and has very little empty return
- *The table top is marked with standard fixed threads to facilitate customers to install relevant accessories by themselves
- *The two-dimensional rotary table can carry out two-axis linkage horizontally and form two-dimensional precise adjustment with its optical products

*The initial zero position is equipped as standard, and the error generated in long-term use can be zeroed and eliminated

	Product model	KYCT120X110D2XZ360M
	Platform size	200X299mm
	Rotation angle	360°
	Material Science	aluminium alloy
	surface treatment	Oxidation blackening
n	load bearing	15kg
p	weight	12. 5kg
a	transmission ratio	180: 1*90:1
r	Driving mechanism	Worm gear and worm mechanism
_	Guide rail form	Bearing
a	electric machinery	Stepper motor (1.8°)
m		0.02° (No subdivision)
e	resolving power	0.001° =3.6" (20subdivision)
t	Empty return	0.005° =18"
U	eccentric	5µ
e	Lose step	0.005° =18"
r	Parallelism	80µ
Need.	Maximum speed	25° /sec*40° /sec
	positioning accuracy	0.005° =18"
	Absolute positioning accuracy	0.01° =36″
	Origin error	±0.03°

